BENDING OF A SANDWICH BEAM WITH AN INDIVIDUAL FUNCTIONALLY GRADED CORE

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This paper is devoted to a clamped sandwich beam with an individual functionally graded core under a uniformly distributed load. A non-linear shear deformation theory is developed with consideration of the classical shear stress formula for beams. Two differential equations of the equilibrium of the beam are obtained based on the principle of stationary total potential energy. The shear effect function and the relative deflection line of the beam are determined. Moreover, a numerical FEM model (Ansys system) of this beam is elaborated. Detailed calculations of exemplary beams are realised using two methods, analytical and numerical FEM.

Keywords: sandwich beam, functionally graded core, non-linear shear deformation theory

1. Introduction

Shear deformation theories of beams, plates and shells have been extensively refined in the twenty-first century. The demand for new, more accurate and generalised shear theories becomes more apparent with increasing interest in the application of composite structures in engineering. The significance of this topic can be proven by the number of articles and original theories developed over the last two decades.


Berdichevsky (2010) derived a two-dimensional theory of sandwich plates by asymptotic analysis of three-dimensional linear elasticity. Carrera et al. (2011) discussed classical and modern approaches to the beam theory and paid particular attention to their typical applications. Meiche et al. (2011) developed an advanced hyperbolic shear deformation theory. Mantari et al. (2012) presented an original shear deformation theory for sandwich and composite plates, where the displacement field is parameterized. Thai and Vo (2013) proposed a sinusoidal shear deformation theory for bending, buckling and vibration of functionally graded plates. Sahoo and Singh (2013) discussed an original inverse trigonometric zigzag theory and implemented it for static analysis of laminated composite and sandwich panels.

Kolakowski and Mania (2015) investigated the dynamic interactive response of square FGM plates subjected to in-plane pulse loading using the modified classical laminate plate theory. Mahi et al. (2015) introduced a hyperbolic shear deformation theory with five degrees of freedom applicable to bending and free vibration analysis of isotropic, functionally graded sandwich and


Kumar et al. (2019) developed a modern higher-order shear deformation theory for a functionally graded plate. Magnucki et al. (2020) referred to the Zhuravsky shear stress formula to develop a shear deformation theory. Żur et al. (2020) focused on buckling and free-vibration analyses of functionally graded nanolayers with magneto-electroelastic coupling. Dhuria et al. (2021) analysed the effect of porosity distribution on the static and buckling response of a simply supported plate with FGM.

Magnucki (2022) presented analytical models of homogeneous beams with bi-symmetrical cross sections, sandwich beams and beams with symmetrically varying mechanical properties. Magnucki et al. (2022) conducted a study on the axisymmetric bending problem of a generalised circular sandwich plate with varying mechanical properties along its thickness. Jędrysiak (2023) investigated slender, elastic, nonperiodic beams with a functionally graded structure on the macro-level and a nonperiodic structure on the micro-level referring to the tolerance modelling method.

The main objective of the study is to formulate a linear theory with the assumption of a non-linear shear deformation for a three-layer beam with an individual functionally graded core. The function of the variation of Young’s modulus is generalised so that it can describe a beam with homogeneous mechanical properties, as well as a classic three-layer and five-layer beam with an optional ratio of stiffness between the layers.

According to the literature review, there are numerous papers investigating the problem of the shear effect in structures. Many of them refer to a numerical approach or analytical formulation with a predefined, usually parametric shear deformation function. In the present paper, the shear deformation function is obtained analytically in the exact manner with consideration of the classical shear stress formula. An analytical model of a beam is developed using the proposed non-linear shear deformation theory. The subject of the study is a clamped sandwich beam of length \( L \), width \( b \), and total depth \( h \) with an individual functionally graded core under a uniformly distributed load of intensity \( q \) (Fig. 1). The bending problem of this beam is studied, taking into account the shear effect. Its solution is compared with the results of numerical finite element method analysis in the Ansys system.

![Fig. 1. A scheme of a clamped sandwich beam with an individual functionally graded core](image)
2. Analytical model of the sandwich beam

The rectangular cross section and variation of Young’s modulus in the depth direction of the beam are shown in Fig. 2.

![Diagram of sandwich beam cross section and Young's modulus variation](image)

Fig. 2. Schemes of the rectangular cross section and variation of Young’s modulus in the depth direction of the beam

The variation of Young’s modulus in the depth direction takes the form

\[ E_f(\eta) = E_f f_e(\eta) \]  
(2.1)

where: \( E_f \) – Young’s modulus of faces, also \( f_e(\eta) \) – dimensionless function, which in successive layers is as follows:

— the upper face \((-1/2 \leq \eta \leq -\chi_c/2)\)

\[ f_e(\eta) = 1 \]  
(2.2)

— the core \((-\chi_c/2 \leq \eta \leq \chi_c/2)\)

\[ f_e(\eta) = e_c + \left(1 - \frac{e_c}{2^n}\right) \cos \left(\frac{4\pi\eta}{\chi_c}\right)^n \]  
(2.3)

— the lower face \((\chi_c/2 \leq \eta \leq 1/2)\)

\[ f_e(\eta) = 1 \]  
(2.4)

and dimensionless quantities: the coordinate \( \eta = y/h \), coefficient of the core \( e_c \), thickness of the core \( \chi_c = h_c/h \), exponent \( n \) – natural number. The deformation of a planar cross section after bending of this beam is presented in Fig. 3. The longitudinal displacements according to this scheme (Fig. 3) in successive layers are as follows:

— the upper face \((-1/2 \leq \eta \leq -\chi_c/2)\)

\[ u^{(af)}(x, \eta) = -h \left[ \frac{dv}{dx} - f_d^{(af)}(\eta) \psi_f(x) \right] \]  
(2.5)
— the core ($-\chi_c/2 \leq \eta \leq \chi_c/2$)

$$u^{(c)}(x, \eta) = -h \left[ \eta \frac{dv}{dx} - f_d^{(c)}(\eta) \psi_f(x) \right]$$

(2.6)

— the lower face ($\chi_c/2 \leq \eta \leq 1/2$)

$$u^{(lf)}(x, \eta) = -h \left[ \eta \frac{dv}{dx} - f_d^{(lf)}(\eta) \psi_f(x) \right]$$

(2.7)

where: $v(x)$ – deflection, $\psi_f(x) = u_f(x)/h$ – dimensionless longitudinal displacement on the outer surfaces of the beam-shear effect function, $f_d^{(uf)}(\eta), f_d^{(c)}(\eta), f_d^{(lf)}(\eta)$ – dimensionless deformation functions in these layers.

Fig. 3. Scheme of a planar cross-section deformation of the analysed beam

Consequently, the strains and stresses are as follows:

— the upper face ($-1/2 \leq \eta \leq -\chi_c/2$)

$$\varepsilon_x^{(uf)}(x, \eta) = \frac{\partial u}{\partial x} = -h \left[ \eta \frac{dv}{dx^2} - f_d^{(uf)}(\eta) \frac{d\psi_f}{dx} \right]$$

$$\sigma_x^{(uf)}(x, \eta) = -E_f h \left[ \eta \frac{dv}{dx^2} - f_d^{(uf)}(\eta) \frac{d\psi_f}{dx} \right]$$

$$\gamma_{xy}^{(uf)}(x, \eta) = \frac{dv}{dx} + \frac{\partial u}{h \partial \eta} = \frac{df_d^{(uf)}}{d\eta} \psi_f(x)$$

$$\tau_{xy}^{(uf)}(x, \eta) = \frac{E_f}{2(1+\nu)} \frac{df_d^{(uf)}}{d\eta} \psi_f(x)$$

(2.8)
— the core \((-\chi_c/2 \leq \eta \leq \chi_c/2)\)

\[
\varepsilon_z^{(c)}(x, \eta) = \frac{\partial u}{\partial x} = -h \left[ \eta \frac{d^2 v}{dx^2} - f_d^{(c)}(\eta) \frac{df_d^{(c)}}{dx} \right]
\]

\[
\gamma_{xy}^{(c)}(x, \eta) = \frac{dv}{dx} + \frac{\partial u}{\partial \eta} = \frac{df_d^{(c)}}{d\eta} \psi_f(x)
\]

\[
\sigma_x^{(c)}(x, \eta) = -E_fh \left[ \eta \frac{d^2 v}{dx^2} - f_d^{(c)}(\eta) \frac{df_d^{(c)}}{dx} \right] f_e^{(c)}(\eta)
\]

\[
\tau_{xy}^{(c)}(x, \eta) = \frac{E_f}{2(1+\nu)} f_e^{(c)}(\eta) \frac{df_d^{(c)}}{d\eta} \psi_f(x)
\]

(2.9)

— the lower face \((\chi_c/2 \leq \eta \leq 1/2)\)

\[
\varepsilon_z^{(lf)}(x, \eta) = \frac{\partial u}{\partial x} = -h \left[ \eta \frac{d^2 v}{dx^2} - f_d^{(lf)}(\eta) \frac{df_d^{(lf)}}{dx} \right]
\]

\[
\gamma_{xy}^{(lf)}(x, \eta) = \frac{dv}{dx} + \frac{\partial u}{\partial \eta} = \frac{df_d^{(lf)}}{d\eta} \psi_f(x)
\]

\[
\sigma_x^{(lf)}(x, \eta) = -E_fh \left[ \eta \frac{d^2 v}{dx^2} - f_d^{(lf)}(\eta) \frac{df_d^{(lf)}}{dx} \right]
\]

\[
\tau_{xy}^{(lf)}(x, \eta) = \frac{E_f}{2(1+\nu)} \frac{df_d^{(lf)}}{d\eta} \psi_f(x)
\]

(2.10)

where \(\nu\) – Poisson’s ratio is constant for the structure. Taking into account the papers by Magnucki (2022) and Magnucki et al. (2022), the unknown dimensionless deformation functions \(f_d^{(af)}(\eta), f_d^{(c)}(\eta), f_d^{(lf)}(\eta)\) are determined with consideration of the classical shear stress formula for the rectangular cross section of the beam

\[
\tau_{xy}^{(cl)}(x, \eta) = \frac{Q_z(\eta)}{J_z} T(x) h^2
\]

(2.11)

where: \(T(x)\) – transverse-shear force, \(Q_z(\eta)\) – dimensionless first moment of the cross section area part, \(J_z\) – inertia moment of the cross section. Therefore, the dimensionless first moments of successive layers of this sandwich beam with the individual functionally graded core are of the form:

— the upper face \((-1/2 \leq \eta \leq -\chi_c/2)\)

\[
\overline{Q}_{z}^{(af)}(\eta) = \frac{1}{8} (1 - 4\eta^2)
\]

(2.12)

— the core \((-\chi_c/2 \leq \eta \leq \chi_c/2)\)

\[
\overline{Q}_{z}^{(c)}(\eta) = \frac{1}{8} \left[ 1 - \chi_c^2 + e_c(\chi_c^2 - 4\eta^2) - 8J_c(\eta) \right]
\]

(2.13)

where

\[
J_c(\eta) = \frac{1 - e_c}{2^n} \int_{-\chi_c/2}^{\eta} \left( 1 + \cos \frac{4\pi \eta_1}{\chi_c} \right)^n \eta_1 \ d\eta_1
\]

(2.14)

— the lower face \((\chi_c/2 \leq \eta \leq 1/2)\)

\[
\overline{Q}_{z}^{(lf)}(\eta) = \frac{1}{8} (1 - 4\eta^2)
\]

(2.15)
Equating the shear stresses in Eqs. (2.8), (2.9) and (2.10) with classical shear stress formula (2.11) with consideration of the dimensionless first moments in Eqs. (2.12), (2.13) and (2.14), after simple transformations, the unknown dimensionless deformation functions for successive layers satisfying the continuity conditions between them are obtained in the following form:

— the upper face \((-1/2 \leq \eta \leq -\chi_c/2)\)

\[
f_\delta^{(u)}(\eta) = -C_f + \frac{1}{24}(3 - 4\eta^2)\eta
\]

(2.16)

— the core \((-\chi_c/2 \leq \eta \leq \chi_c/2)\)

\[
f_\delta^{(c)}(\eta) = \int_0^{Q_z^{(c)}(\eta)} \frac{f_e(\eta)}{f_e(\eta)} d\eta
\]

(2.17)

— the lower face \((\chi_c/2 \leq \eta \leq 1/2)\)

\[
f_\delta^{(u)}(\eta) = C_f + \frac{1}{24}(3 - 4\eta^2)\eta
\]

(2.18)

where the dimensionless coefficient

\[
C_f = -\frac{1}{48}(3 - \chi_c^2)\chi_c + \int_0^{\chi_c/2} \frac{Q_z^{(c)}(\eta)}{f_e(\eta)} d\eta
\]

(2.19)

The graph of dimensionless functions in Eqs. (2.2), (2.3) and (2.4) of the variation of Young’s modulus and the shape of deformation of the planar cross section of an exemplary beam \((\chi_c = 4/5, \; e_c = 1/30, \; n = 7)\), taking into account functions Eqs. (2.16), (2.17) and (2.8), is shown in Fig. 4.

Fig. 4. The graph of dimensionless functions of Young’s modulus variation and the shape of deformation of the planar cross section of the exemplary beam
3. Analytical bending study of the sandwich beam

The elastic strain energy is described as

\[ U_e = \frac{1}{2} E_f bh \int_0^L \left[ \Phi^{(u)}_{ε,γ}(x) + \Phi^{(c)}_{ε,γ}(x) + \Phi^{(f)}_{ε,γ}(x) \right] dx \]  \hspace{1cm} (3.1)

where

\[ \Phi^{(u)}_{ε,γ}(x) = \int_{-\chi_e/2}^{\chi_e/2} \left\{ \left[ \varepsilon^{(u)}_{ε,γ}(x, η) \right]^2 + \frac{1}{2(1+ν)} \left[ \gamma^{(u)}_{xy}(x, η) \right]^2 \right\} dη \]

\[ \Phi^{(c)}_{ε,γ}(x) = \int_{-\chi_e/2}^{\chi_e/2} \left\{ \left[ \varepsilon^{(c)}_{ε,γ}(x, η) \right]^2 + \frac{1}{2(1+ν)} \left[ \gamma^{(c)}_{xy}(x, η) \right]^2 \right\} f_ε(η) dη \]

\[ \Phi^{(f)}_{ε,γ}(x) = \int_{-\chi_e/2}^{\chi_e/2} \left\{ \left[ \varepsilon^{(f)}_{ε,γ}(x, η) \right]^2 + \frac{1}{2(1+ν)} \left[ \gamma^{(f)}_{xy}(x, η) \right]^2 \right\} dη \]

Substituting expressions in Eqs. (2.8), (2.9), (2.10) for strains into Eq. (3.1), after integration, one obtains

\[ U_e = \frac{1}{24} E_f bh^3 \int_0^L \left[ C_{vv} \left( \frac{d^2 v}{dx^2} \right)^2 - 2C_{vv} \frac{d^2 v}{dx^2} \frac{d \psi_f}{dx} + C_{\psi \psi} \left( \frac{d \psi_f}{dx} \right)^2 + C_{\psi} \frac{\psi_f(x)^2}{h^2} \right] dx \]  \hspace{1cm} (3.2)

where the dimensionless coefficients

\[ C_{vv} = 1 - \chi_e^3 + 12J_{vv} \]

\[ C_{\psi \psi} = 3(1 - \chi_e^3)C_f + \frac{1}{40}(4 - 5\chi_e^3 + \chi_e^5) + 12J_{\psi \psi} \]

\[ C_{\psi} = \frac{1}{2(1+ν)} \left\{ \frac{1}{80} \left[ 84[96(1 - \chi_e)C_f + 5 - 6\chi_e^2 + \chi_e^4]C_f \\
+ \frac{1}{10}(68 - 105\chi_e^2 + 42\chi_e^5 - 5\chi_e^7) \right] + 12J_{\psi} \right\} \]

\[ J_{vv} = \int_{-\chi_e/2}^{\chi_e/2} \eta^2 f_ε(η) dη \]

\[ J_{\psi \psi} = \int_{-\chi_e/2}^{\chi_e/2} \left( \frac{d \psi_f}{d\eta} \right)^2 f_ε(η) d\eta \]

\[ J_{\psi} = \int_{-\chi_e/2}^{\chi_e/2} \frac{\psi_f(x)^2}{h^2} f_ε(η) d\eta \]

The work of the load is in the form

\[ W = \int_0^L qv(x) \, dx \]  \hspace{1cm} (3.3)

Based on the principle of stationary total potential energy \( δ(U_e - W) = 0 \), the system of two differential equations of equilibrium of this sandwich beam is obtained in the following form

\[ C_{vv} \frac{d^4 v}{dx^4} - C_{\psi \psi} \frac{d^3 \psi_f}{dx^3} = \frac{q}{E_f bh^3} \]

\[ C_{\psi \psi} \frac{d^3 v}{dx^3} - C_{vv} \frac{d^2 \psi_f}{dx^2} + C_{\psi} \frac{\psi_f(x)}{h^2} = 0 \]  \hspace{1cm} (3.4)
The fourth-order expression, Eq. (3.4)\textsubscript{1}, of this system is equivalent to the second-order equation of the form
\[ C_{vv} \frac{d^2 v}{dx^2} - C_{v\psi} \frac{dv_f}{dx} = - \frac{M_b(x)}{E_f bh} \]  
(3.5)

where \( M_b(x) \) is the bending moment. Thus, Eqs. (3.5) and (3.4)\textsubscript{2} are the governing equations of the sandwich beam. These two equations, after a simple transformation, are reduced to one equation in the form
\[ \frac{d^2 \psi_f}{d\xi^2} - (\alpha \lambda)^2 \psi_f(\xi) = - \frac{C_{v\psi}}{C_{vv}C_{\psi\psi} - C_{v\psi}^2} \lambda^2 T(\xi) \frac{E_f b}{E_f b} \]  
(3.6)

where: \( \xi = x/L \) – dimensionless coordinate, \( \lambda = L/h \) – relative length of the beam, and
\[ \alpha = \sqrt{\frac{C_{vv}C_{\psi}}{C_{vv}C_{\psi\psi} - C_{v\psi}^2}} \]

is a dimensionless coefficient. The end part of this beam with a uniformly distributed load and reactions is shown in Fig. 5.

Fig. 5. Scheme of the beam end part with the load end reactions

The bending moment and the shear force according to this scheme, in the dimensionless coordinate \( \xi \), are as follows
\[ M_0(\xi) = \frac{1}{2}\xi - \xi^2 - 2M_c qL^2 \quad T(\xi) = \frac{1}{2}(1 - 2\xi)qL \]  
(3.7)

where \( M_c = M_c/(qL^2) \) is the unknown dimensionless reactive moment. Therefore, Eq. (3.6), taking into account the transverse shear force in Eq. (3.7)\textsubscript{2}, is of the form
\[ \frac{d^2 \psi_f}{d\xi^2} - (\alpha \lambda)^2 \psi_f(\xi) = -6 \frac{C_{v\psi}}{C_{vv}C_{\psi\psi} - C_{v\psi}^2} \lambda^2 (1 - 2\xi^2) \frac{q}{E_f b} \]  
(3.8)

The solution of this equation is as follows
\[ \psi_f(\xi) = [C_1 \sinh(\alpha \lambda \xi) + C_2 \cosh(\alpha \lambda \xi) + C_0(1 - 2\xi)] \frac{q}{E_f b} \]  
(3.9)

where \( C_1, C_2 \) are integration constants, and
\[ C_0 = 6 \frac{C_{v\psi}}{C_{vv}C_{\psi}} \lambda \]

Taking into account the two conditions: \( \psi_f(0) = 0 \) – clamped end, and \( \psi_f(1/2) = 0 \) – the symmetry plane of the beam, these constants are as follows \( C_1 = C_0/\tanh(\alpha \lambda/2) \) and \( C_2 = -C_0 \). Consequently, the function in Eq. (3.9), that is, the shear effect function is in the following form
\[ \psi_f(\xi) = \overline{\psi}_f(\xi) \frac{q}{E_f b} \]  
(3.10)
where
\[
\overline{\psi}_f(\xi) = 6\left\{ 1 - 2\xi - \frac{\sinh[\alpha\lambda(1 - 2\xi)/2]}{\sinh(\alpha\lambda)/2} \right\} \frac{C_{vw}}{C_{vv}C_\psi}\lambda
\]  
(3.11)

Equation (3.5) in the dimensionless coordinate, with consideration of the expressions in Eqs. (3.7) and (3.10), is as follows
\[
d_2^2 \tau d\xi^2 = \left[ \frac{C_{vw}}{\lambda^3} \frac{d\overline{\psi}_f}{d\xi} - 6(\xi - \xi^2 - 2M_c) \right] \frac{\lambda^3}{C_{vv}} \frac{q}{E_f b}
\]  
(3.12)

where \(\overline{\psi}(\xi) = \psi(\xi)/L\) is the relative deflection of the beam. Integrating this equation and taking into account the boundary condition \(d\tau/d\xi\bigg|_0 = 0\) – clamped end, and \(d\tau/d\xi\bigg|_{1/2} = 0\) – symmetry plane of the beam, one obtains
\[
d_\tau = \left[ \frac{C_{vw}}{\lambda^3} \overline{\psi}_f(\xi) - 6\left( \frac{1}{2}\xi^2 - \frac{1}{3}\xi^3 - 2M_c \xi \right) \right] \frac{\lambda^3}{C_{vv}} \frac{q}{E_f b}
\]  
(3.13)

where: \(M_c = 1/12\). Thus, integrating this equation and taking into account the boundary condition \(\tau(0) = 0\) and the function in Eq. (3.11), one obtains the relative deflection-bending line of the beam
\[
\overline{\tau}(\xi) = \overline{\tau}(\xi) \frac{q}{E_f b}
\]  
(3.14)

where
\[
\overline{\tau}(\xi) = \left[ 6f_\psi(\xi) \frac{C_{ps}}{C_{vv}C_\psi} \frac{1}{\lambda^2} - \frac{1}{2}(2\xi - \xi^2 - 1) \xi^2 \right] \frac{\lambda^3}{C_{vv}}
\]  
(3.15)

Consequently, the relative maximum deflection
\[
\overline{\tau}_{\text{max}} = \overline{\tau}\left(\frac{1}{2}\right) = \overline{\tau}_{\text{max}} \frac{q}{E_f b}
\]  
(3.16)

where the dimensionless maximum deflection
\[
\overline{\tau}_{\text{max}} = \overline{\tau}\left(\frac{1}{2}\right) = (1 + C_{se}) \frac{\lambda}{32C_{vv}}
\]  
(3.17)

and the shear coefficient
\[
C_{se} = 48 \left[ 1 - 4 \frac{\cosh(\alpha\lambda/2)}{\alpha\lambda\sinh(\alpha\lambda/2)} \right] \frac{C_{ps}^2}{C_{vv}C_\psi}\lambda^2
\]  
(3.18)

The shear stresses described by Eqs. (2.8), (2.9) and (2.10), with consideration of Eqs. (2.16), (2.17) and (2.18), in successive layers, are as follows:
— the upper face \((-1/2 \leq \eta \leq -\chi_c/2)\)
\[
\tau_{xy}(u) = \frac{q}{b} \overline{\tau}_{xy}(u)(x, \eta)
\]  
(3.19)

where, the dimensionless stress
\[
\overline{\tau}_{xy}(u) = \frac{1}{2(1 + \nu)} \frac{Q_z(u)}{\psi_f(x)}
\]  
(3.20)
— the core \((-\chi_c/2 \leq \eta \leq \chi_c/2)\)

\[
\tau_{xy}^{(c)}(x, \eta) = \frac{1}{2(1+\nu)} Q_z^{(c)} (x) \psi_f(x)
\] (3.21)

— the lower face \((\chi_c/2 \leq \eta \leq 1/2)\)

\[
\tau_{xy}^{(lf)}(x, \eta) = \frac{1}{2(1+\nu)} Q_z^{(lf)} (x) \psi_f(x)
\] (3.22)

Exemplary calculations are carried out for a beam family of the following selected dimensionless sizes and material constants: \(\lambda = 30, \chi_c = 4/5, \varepsilon_c = 1/30, \nu = 0.3\), as well as the exponent – natural number \(n = 0, 2, 7, 14, 25, \rightarrow \infty\). The graphs of the dimensionless functions given in Eqs. (2.2), (2.3) and (2.4) of Young’s modulus variation and the dimensionless shear stresses in Eqs. (3.20), (3.21) and (3.22) in the beam cross section for \(\xi = 0.1\), and the exponent value \(n = 7, \rightarrow \infty\) are shown in Figs. 6a and 6b. The maximum shear stress \(\tau_{\max}(\xi) = \tau_{xy}^{(c)}(\xi, 0)\) occurs at the neutral surface \(\eta = 0\) in the core.

![Graphs](image)

Fig. 6. The graph of dimensionless functions of Young’s modulus variation and the dimensionless shear stress: (a) for \(n = 7\) and (b) classical sandwich beam for \(n \rightarrow \infty\)

The results of analytical calculations of the dimensionless coefficient \(C_{vv}\), maximum dimensionless shear stresses, shear coefficient \(C_{se}\), Eq. (3.18), and dimensionless maximum deflection \(v_{\max}\), Eq. (3.17), are specified in Table 1.

**Table 1.** The value of coefficients, shear stresses and maximum deflections – analytical calculations

<table>
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<tr>
<th></th>
<th>(n)</th>
<th>0</th>
<th>2</th>
<th>7</th>
<th>14</th>
<th>25</th>
<th>(\infty)</th>
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<td>0.09186</td>
<td>0.13953</td>
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<td>0.15996</td>
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<td></td>
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Moreover, the graphs of maximum dimensionless shear stresses \(\tau_{\max}\) and maximum deflections \(v_{\max}\) are shown in Figs. 7a and 7b.
4. Numerical FEM bending study of the sandwich beam

The numerical model of the family of selected beams with the same parameters as in the analytical study is developed in the Ansys 2021 R2 system and is examine in linear static structural analysis. The following parameters are applied in the study: $E_f = 70\,\text{GPa}$, $b = 50\,\text{mm}$, $h = 50\,\text{mm}$, thus $L = 1500\,\text{mm}$ ($\lambda = 1/30$).

Due to symmetry of the geometry, load and mechanical parameters, only a quarter of the beam is considered. The symmetric boundary conditions are applied by restricting the normal displacements at the selected faces shown in Fig. 8a. The clamped boundary condition is imposed on the face of the free end of the beam in the following manner. Displacements along the $y$-axis are blocked referring to the remote point located in the centre of the coordinate system ($v = 0$). In addition, the translations towards the $x$-axis are restrained globally ($u = 0$) on the same face. Such a boundary condition is consistent with analytical study and also allows deformations of the face at the end of the beam in the $y$ and $z$ directions, which ensures no stress concentration phenomenon. The force $F_y = 1\,\text{kN}$ is applied to the top of the quarter of the model, which corresponds to the uniformly distributed load (Fig. 1) of $q = 8/3\,\text{N/mm}$.

The geometry is divided into uniform second-order hexahedral SOLID186 finite elements with twenty nodes and three degrees of freedom at each node (Fig. 8b). A sufficient number of finite elements is found through mesh convergence study with the accuracy criterion imposed on the maximum deflection, shear stress, and elastic strain energy. Such an analysis is carried out assuming the greatest gradient of Young’s modulus except for $n \to \infty$, that is, for $n = 25$. The finite element model consists of over 1.3 million nodes and 312 thousand elements, assuming there are 300, 80 and 13 elements along $x$, $y$ and $z$ directions (Fig. 8a), respectively. The ratio
of the number of elements to the model size is highest along the depth of the beam (y-axis) due to the variable mechanical property towards this direction.

The mechanical properties of the material are coherent with analytical study, i.e. isotropic, perfectly elastic, where Young’s modulus is described by the function in Eqs. (2.1) and (2.3). At any point of the geometry, the calculated values of Young’s modulus are mapped to the centres of hexahedral finite elements. An exemplary distribution of Young’s modulus for \( n = 2 \) is shown in Fig. 9.

![Fig. 9. Young’s modulus \( E \) distribution for \( n = 2 \)](image)

The deflections \( v \) obtained for this case, i.e. displacements toward the y-axis, are shown in Fig. 10a. Following the analytical study, the shear stress is studied for \( \xi = x/L = 0.1 \). In that case, the surface at \( x = 150 \text{ mm} \) parallel to the \( yz \) plane is considered as presented in Fig. 10b.

![Fig. 10. (a) Deflections \( v(x) \) for \( n = 2 \). (b) Shear stress \( \tau_{xy} \) in the surface parallel to \( yz \) plane at \( x = 150 \text{ mm} \) (\( \xi = x/L = 0.1 \)) for \( n = 2 \)](image)

The results of the numerical study are further compared with the analytical solutions. It should be noted that in the case of a three-dimensional finite element model, the shear stress \( \tau_{xy} \) varies along the width of the beam (Fig. 10b). To study the results, the mean of that function along width is considered. The maximum deflection \( v_{\text{max}} \) in FEM analyses are taken from the neutral surface for \( z = 0 \). To maintain consistency with the analytical study, the obtained results are further considered in a dimensionless form, that is

\[
\begin{align*}
\tau_{\text{max}} &= \frac{E_f b}{q L} v_{\text{max}} \\
v_{\text{max}} &= \frac{b}{q} \tau_{\text{max}}
\end{align*}
\]  

(4.1)

Exemplary distributions of shear stress along the depth of the beam described by the dimensionless parameter \( \eta \) and corresponding dimensionless functions of Young’s modulus are presented in Figs. 11a and 11b. These show a near-perfect agreement with the analytical outcomes shown in Figs. 6a and 5b.
The numerically obtained maxima of shear stress $\tau_{\text{max}}$ and deflections $v_{\text{max}}$ for all the values considered of the parameter $n$ are summarised in Table 2 in a dimensionless form. When comparing the dimensionless maximum shear stresses and deflections calculated analytically and numerically (Tables 1 and 2), it is easy to notice that the differences between them are insignificant, less than 0.1%.

**Table 2.** The maximum shear stresses and deflections – numerical FEM analysis

<table>
<thead>
<tr>
<th>$n$</th>
<th>0</th>
<th>2</th>
<th>7</th>
<th>14</th>
<th>25</th>
<th>$\infty$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\tau_{\text{max}}$</td>
<td>18.0023</td>
<td>15.1169</td>
<td>14.3331</td>
<td>14.0808</td>
<td>13.9379</td>
<td>13.5904</td>
</tr>
<tr>
<td>$v_{\text{max}}$</td>
<td>854.9</td>
<td>1261.0</td>
<td>1497.7</td>
<td>1605.6</td>
<td>1680.4</td>
<td>1956.9</td>
</tr>
</tbody>
</table>

5. Conclusions

Most of the papers investigating the problem of the shear effect in beams refer to numerical methods or analytical studies, whereas the deformation function is assumed in advance within the number of theories mentioned in the literature review. The choice of the deformation function can have a direct effect on the accuracy of the solution. In the present paper, a linear theory with the assumption of nonlinear shear deformation is developed and applied taking into account the classical shear stress formula for beams. Unlike the number of theories and papers, the shear deformation function is the result of an analytical solution, which leads to an exceptionally coherent solution compared to the FEM study.

The generalised form of the function that describes Young’s modulus allowed us to analyse beams with various mechanical properties, including homogeneous and layered beams within the proposed theory. Using the principle of stationary potential energy, two differential equations of equilibrium were derived and then solved. Relative deflections and shear stresses were calculated for exemplary beams with different variations in Young’s modulus.

To verify the accuracy of the developed theory, the outcome of the analytical study was compared with the results of numerical FEM analysis in the Ansys system. The beam was...
modelled as a three-layered structure, while its core had a variable Young’s modulus along its depth.

Following the results in Figs. 6 and 12, both analytical and numerical analyses yielded consistent shear stress distributions for all exemplary structures. Comparison of the maximum relative deflection and maximum relative shear stress shown in Tables 1 and 2 shows a nearly identical result from both methods. The relative differences between these are less than 0.1%, proving that the theory developed is accurate. Having in mind the fact that it is suitable for beams with different Young’s modulus distributions, i.e. homogenous and nonhomogeneous, it can be applied to numerous practical analyses of composite structures.

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